

IMAGE PROCESSING METHOD, IMAGE PROCESSING APPARATUS
AND IMAGE PROCESSING PROGRAM

BACKGROUND OF THE INVENTION

5 Field of the Invention

The present invention relates to an image processing method, an image processing apparatus and an image processing program.

Related Background Art

10 In recent years, information has been increasingly electrified, and thus demand for converting a paper document and an electrified document into each other has been growing. For electrifying a paper document, it is desirable that
15 the printed side of a paper is not just photoelectric-converted into image data using a scanner or the like, but a document image is divided into areas of different natures such as texts, symbols, graphics, photographs and tables, and an
20 optimum format of data is applied for each area such as character code information for character portions, vector data for graphics, lines and table frames, image data for photographs and structural data for contents of tables.

25 In this way, in processing for electrifying a paper document, processing for analyzing the contents written in a document image to divide the contents

into sectional areas of different natures such as characters, graphics, photographs and tables, namely area division processing is of great importance.

For the methodology of this area division processing, it has been proposed, for example, that a document image read with multi-values (grayscale or color) as shown in Fig. 21 is converted into a binary image with a difference in luminance, pixel blocks having black pixels in outlines, existing in the image, are all extracted and classified into characters and non-characters according to their sizes, and pixels are searched recursively from the insides of white pixel areas existing in non-character large black pixel blocks, whereby a situation of pixel blocks is expressed with a hierarchical tree structure shown in Fig. 16. The image is divided into areas having a variety of attributes by processing of grouping character pixel blocks present in the same level of hierarchy to obtain a character area, obtaining graphics and photograph areas from the shapes of non-character pixel blocks and peripheral conditions, obtaining a front area as a set of pixels constituting a hierarchy, and so on, for the tree structure of pixel blocks, whereby an area division result shown in Fig. 22 can be obtained. Furthermore, at this time, information suitable for determination of logical

structure of a document is provided by making each area having a tree structure shown in Fig. 23.

In this area division processing, however, it is not easy to sample an area of luminance inverted characters included in Fig. 21, namely an area of characters constituted not by black-on-white pixels but by white-on-black pixels (inverted character, outlined character) on a binary image, in terms of configuration of processing. In addition, it has been proposed that the numbers of black and white pixels are compared to each other, and the pixels are inverted if it is determined that the number of black pixels is larger, whereby inverted characters can be recognized, but it is difficult to obtain a correlation between normal characters and inverted characters, and it is thus impossible to obtain from a document including both normal characters and inverted characters a tree structure dealing with collectively normal characters and inverted characters of the document.

SUMMARY OF THE INVENTION

For solving the problems described above, the present invention is characterized in that black pixel blocks and white pixel blocks are sampled recursively from a binary image, tree structure data indicating a positional relation between the sampled

black pixel blocks and white pixel blocks is created,
an inverted image is created by white-black-inverting
the insides of black pixel blocks that can include
inverted characters, of black pixel blocks included
5 in the tree structure data, white pixel blocks and
black pixel blacks are sampled from the created
inverted image, and data regarding the sampled white
pixel blocks and black pixel blocs is added to
corresponding nodes of the tree structure data.
10 Other features and advantages of the present
invention will be apparent from the following
description taken in conjunction with the
accompanying drawings, in which like reference
characters designate the same or similar parts
15 throughout the figures thereof.

BRIEF DESCRIPTION OF THE DRAWINGS

The accompanying drawings, which are
incorporated in and constitute a part of the
20 specification, illustrate embodiments of the
invention and, together with the description, serve
to explain the principles of the invention.

Fig. 1 is a block diagram showing a
configuration of the first embodiment;

25 Fig. 2 shows an example of a configuration of
apparatus to realize the first embodiment;

Fig. 3 is a flowchart for explaining area.

division processing of the first embodiment;

Fig. 4 is a flowchart for explaining pixel block sampling processing;

Fig. 5 is a flowchart for explaining processing
5 of tracking the outline of black pixels;

Fig. 6 is a flowchart for explaining inverted character sampling processing;

Fig. 7 is a flowchart for explaining area classification processing;

10 Fig. 8 shows an example of pixel block sampling processing by outline tracking;

Fig. 9 shows an example of inverted character sampling processing;

Fig. 10 shows eight tracking directions;

15 Fig. 11 shows a table for determining tracking directions;

Fig. 12 shows a table for obtaining a label to be applied to a referred pixel;

20 Fig. 13 shows examples of rectangular black pixel blocks and non-rectangular black pixel blocks;

Figs. 14A, 14B and 14C show examples of arrangement states of white pixels blocks in black pixel blocks;

25 Fig. 15 shows an example of a binary image as an input of area division processing;

Fig. 16 shows an example of a tree structure of pixel blocks;

Fig. 17 shows an example of an image created for sampling inverted characters;

Fig. 18 shows an example of a tree structure of pixel blocks to which inverted characters are
5 applied;

Fig. 19 shows an example of processing of division of an area including inverted character parts;

Fig. 20 shows an example of a tree structure of
10 an area including inverted character parts;

Fig. 21 shows an example of a document original to be subjected to area division;

Fig. 22 shows an example of the result of conventional area division; and

15 Fig. 23 shows an example of a conventional area tree structure.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

A block diagram of this embodiment is shown in
20 Fig. 1.

Reference numeral 101 denotes an input unit for inputting image data created by photoelectric-converting a paper document, reference numeral 102 denotes a preprocessing unit for subjecting inputted
25 image data to preprocessing such as binarization, size reduction and noise reduction, and reference numeral 103 denotes an area division unit for

dividing image data into areas for attributes such as characters, lines, graphics and tables. Furthermore, the area division unit 103 is comprised of a pixel block sampling unit 1031 for sampling black pixel blocks and white pixel block to create a tree structure data (hierarchical structure data) of pixel blocks, an inverted pixel block sampling unit 1032 for adding inverted character information to tree structure data of pixel blocks, and an area definition unit 1033 for classifying areas for attributes in tree structure data of pixel blocks. Reference numeral 104 denotes an output unit for outputting information of the result of performing division of areas obtained from an image (tree structure data of areas).

A schematic diagram of a configuration of apparatus for realizing this embodiment is shown in Fig. 2. A scanner apparatus 201 performs a photoelectric conversion operation of the input unit 101 to input image data. A computer apparatus 202 performs preprocessing 102 and area division processing 103, and receives operational control from a user through instruction means 203 such as a keyboard and a mouse. Data created by area division processing is outputted to a storage medium installed in a computer such as a hard disk, a display 204, a printer 205, other apparatuses via a network, and the

like.

Furthermore, the computer apparatus for performing this embodiment is comprised of a CPU for performing actual process operations, an RAM for
5 reading a program for use as a work area, storage media for storing programs for performing processing corresponding to flowcharts to be described later, and various kinds of data (hard disk, ROM, removal disk (floppy (R) disk, CD-ROM, etc.) or the like), a
10 keyboard and a pointing device for carrying out various kinds of operations, a display for displaying a document or the like to be processed, a network interface for establishing connection with a network, and the like. An image processing program to be
15 executed by the CPU may be supplied from the storage medium, or may be read from an external apparatus via a network. Furthermore, a program is executed in CPU to realize this embodiment, but part or all of the processing thereof may be performed by hardware
20 (electric circuit).

The procedure of image processing performed in this embodiment will be described using Fig. 4.

At step S301, a paper document is read by a scanner or the like to create image data, and the
25 image data is inputted to the computer.

At step S302, image data is converted into a binary image suitable for performing subsequent area

division processing in the preprocessing unit 102. Specifically, if the inputted image data is a multi-valued image such as color or gray scale, binarization processing for adaptively setting a
5 threshold value and converting the image data into a binary (in this embodiment, the pixel value of a black pixel is considered as 1, and the pixel value of a white pixel is considered as 0), and noise reduction processing for removing isolated points and
10 the like are carried out. Furthermore, for carrying out processing of area division of the image at a high speed, processing for changing the size of inputted image data to an appropriate image size (conversion of resolution of document images) may be
15 carried out. For example, the processing is carried out by OR scaledown such that the pixel value is set to a representative value 0 when the values of pixels in the 2×2 range are all 0 if the image resolution is reduced to $1/2$ (when the values of pixels in the 4
20 $\times 4$ range are all 0 if the image resolution is reduced to $1/4$), and the pixel value is set to 1 in other cases.

At step S303, pixel block sampling processing 1031 in the area division unit 103 is performed, in
25 which blocks of black pixels and white pixels are recursively sampled to create a tree structure. This pixel block sampling processing will be described in

detail using the flowchart of Fig. 4.

At step S401, a black pixel block surrounded by 8 connected lines is sampled. Processing proceeds to S402 if the black pixel block can be sampled, and
5 processing proceeds to S408 if it cannot be sampled. Furthermore, the black pixel block surrounded by 8 connected lines refers to a set (area) of black pixels sampled by detecting black pixels contacting in any of longitudinal, lateral and slanting
10 directions to track the outline of a set of black pixels. Hereinafter, this set is referred to as a black pixel block. Furthermore, this black pixel block is independent of whether pixels other than outline pixels are white or black, and may have voids
15 of white pixels therein. Furthermore, for the method for tracking the outline of these black pixels, a well known method can be used, and the outline of black pixel block sampling processing will be briefly described below using Fig. 5.

20 At step S501, a binary image (constituted by white pixel value 0 and black pixel value 1) is line-scanned in order from top-left to search a point having a pixel value of 1 (black pixel). For example, the image is scanned on a line-by-line basis to
25 search a black pixel in an order shown by the arrow of 801 in Fig. 8.

At step S502, whether a black pixel has been

found or not is determined, and if the black pixel has been found, processing proceeds to step S503, where outline sampling processing is started, with the black pixel as a starting point and also referred
5 point Q. On the other hand, it is determined at step S502 that no black pixel has been found, processing is ended. For example, a pixel 810 is a starting point and also first referred point Q in Fig. 8.

At step S503, peripheral pixels are checked in
10 an order described in the table of Fig. 11 based on a preceding tracking direction d (direction of tracking from a preceding pixel toward the referred point Q) and states of peripheral pixels, whereby a tracking direction d' from the referred point Q to a next
15 outline pixel is defined. Here, the tracking direction is represented by any of eight directions N, NE, E, SE, S, SW, W and NW as shown in Fig. 10. In addition, as exceptional processing, the preceding tracking direction d is defined as SE at the first
20 referred point Q (starting point). The table shown in Fig. 11 shows an order n in which pixels around the referred point Q is checked with respect to the preceding tracking direction d. If the preceding tracking direction d is SW, for example, peripheral
25 pixels are checked counterclockwise in order from pixels in the NW direction when viewed from the referred point Q (pixels in the NW direction, pixels

in the W direction, pixels in the SW direction ...
are checked in this order), and at the time when a
black pixel is found, the checking of peripheral
images is ended, and the direction in which the black
5 pixel is found is defined as the tracking direction
d'. By checking peripheral images in the order shown
in Fig. 11, pixels checked in defining the preceding
tracking direction d are prevented from being checked
when the next tracking direction d' is defined.

10 At step S504, a label indicating an outline
pixel is applied to the pixel of the referred point Q.
There are four types of labels, i.e. "A", "B", "C"
and "D", and in the area surrounded by the outline,
the label A is applied to pixels corresponding to the
15 edge of the left end, the label B is applied to
pixels corresponding to the edge of the right end,
the label C is applied to pixels corresponding to
both left and right edges, and the label D is applied
to outline pixels corresponding to neither left nor
20 right edges. This label value is determined from the
preceding tracking direction d and next tracking
direction d' and the current label value of Q by
using Figs. 11 and 12.

At step S505, a pixel in the next tracking
25 direction d' is defined as a new referred point Q,
and the tracking direction d' is substituted in the
preceding tracking direction d.

At step S506, whether the new referred point Q equals the starting point or not is determined, and if it equals the starting point, then processing proceeds to step S507, and if it does not equal the
5 starting point, then processing returns to step S503, where tracking processing is carried out again.

Processing performed at steps S503 to 506 will be described using an example 801 in Fig. 8 as an example. First, the starting point 810 is defined as
10 a first referred point Q, and pixels are checked from pixels in the direction SW in the order shown in Fig. 11. Here, a black pixel is found in the next tracking direction $d'=SW$ ($n=1$) from the first referred point Q (810), and referring to Fig. 12, the
15 label "A" is applied to the referred point Q (pixel 810), and thereafter the referred point Q moves to lower-left. Subsequently, processing is repeated in the same manner to obtain an outline labeled as shown in an example 802 in Fig. 8.

20 At step S507, whether an additional branch exists in the referred point Q (starting point) is checked. The determination of whether an additional branch exists is made if the preceding tracking direction d is NE, and it is determined that no
25 additional branch exists if the preceding tracking direction is not NE. If the preceding tracking direction d is NE, pixels in the SE direction and

pixels in the E direction are checked in this order when viewed from the referred point Q to determine whether a black pixel exists for pixels around the referred point Q, and at the time when a black pixel
5 is found, it is determined that an additional branch exists, and the referred point Q is moved in the direction d' in which the branch exists and the tracking direction d' is substituted in the preceding tracking direction d, and then processing returns to
10 step S503. On the other hand, if no additional branch exists, processing proceeds to step S509.

At step S509, a block of pixels surrounded by outline-labeled black pixels is recorded as one black pixel block. Specifically, as an example 803 in Fig.
15 8, sequent pixels between a pair of the left edge label "A" and the right edge label "B", or a single "C" pixel are defined as one segment for each y coordinate (pixel line), and a pixel block is recorded as a set of the segments. Furthermore, in
20 the example 803 in Fig. 8, for the sake of easy explanation x and y coordinates have as an origin a rectangular upper-left point circumscribed with the black pixel block, but preferably the x and y coordinates have as an origin an upper-left point of
25 the image scaled down at S302.

Furthermore, after the sampling of one pixel block is completed (after processing at S509 is

completed), the sampled pixel block is subjected to attribute classification at steps S402 to S407, and then processing returns to S501, where line scanning is carried out again beginning with a pixel adjacent
5 to the previous starting point on the right side to search a next starting point. However, searching is skipped for pixels insides the outlines of black pixel blocks already obtained at this time, namely a pixel of pixel value = "1" is searched ignoring
10 pixels overlapping with segments of black pixel blocks already found.

Referring to Fig. 4 again, attributes are classified in processing subsequent to step S402 using the shapes of black pixel blocks and the shapes
15 of circumscribed rectangles circumscribed with black pixel blocks for all black pixel blocks sampled in processing at step S401 (processing in Fig. 5).

At step S402, if the size of the subscribed rectangle of a black pixel block is equal to or less
20 than a threshold value predefined for a maximum character height and width predicted in advance, it is determined that the black pixel block is a character element. An attribute of "CHAR" is given to this black pixel block.

25 At step S403, the subscribed rectangular of a black pixel block is longitudinally long or laterally long in size in a ratio equal to or greater than a

predetermined ratio, an attribute of "LINE" is given to the black pixel block.

At step S404, attention is focused on an outline constituted by black pixels in a black pixel block, and if it is determined that the shape thereof is of slender slanting line, an attribute of "LINE" is given to the black pixel block.

At step S405, white pixel blocks surrounded by 4 connected lines existing in black pixel blocks other than "CHAR" and "LINE" are sampled. The white pixel block surrounded by 4 connected lines is a pixel set surrounded by an outline of longitudinally and laterally connected white pixels. Hereinafter, this set is referred to as a white pixel block.

The method for sampling a white pixel block is such that in black pixel outline sampling processing described with Fig. 5, "0" and "1" are inverted, and only connected lines in longitudinal and lateral four directions (N, E, S, W) are permitted with no consideration given to connected lines in slanting directions to sample an outline of white pixels. Otherwise, the track may move out of the black pixel block having a referred point as a base. Because of this limitation, similar processing is carried out without making determinations for slanting directions as tracking directions, in tables of Figs. 11 and 12, in processing equivalent to step S503 in Fig. 5.

Furthermore, a table for tracking an outline of white pixels may be prepared instead of the tables of FIGS 11 and 12 and in this case, the table is very small because there are only four tracking directions.

5 At step S406, whether the outline of black pixels is almost rectangular in shape is checked, and if it is almost rectangular, processing proceeds to step S407. If it is not almost rectangular, it is determined that the black pixel block is "NONCHAR".
10 Examples of rectangular black pixel blocks and non-rectangular black pixel blocks are shown in Fig. 13.

 At step S407, it is determined that the arrangement of white pixel blocks is good if all white pixel blocks sampled from the inside of the
15 black pixel block considered as being almost rectangular in shape are almost oblong in shape, and they occupy the inside of the black pixel block leaving almost no gaps (subscribed rectangles of white pixel blocks do not overlap one another so that
20 the white pixel blocks are arranged orderly). An attribute of "TABLE" is given to a black pixel block in which the arrangement of internal white pixel blocks is good, while an attribute of "NONCHAR" is given to a black pixel block in which the arrangement
25 of internal white pixel blocks is bad. Examples of arrangement of internal white pixel blocks are shown in Figs. 14A to 14C. Figs. 14A and 14B show examples

of black pixel blocks classified as "TABLE" because the arrangement of internal white pixel blocks is good, and Fig. 14C shows an example of a black pixel block classified as "NONCHAR" because the arrangement
5 of internal white pixel blocks is bad.

At step S408, with attention focused on white pixel blocks existing in a black pixel block classified as "NONCHAR" or "TABLE", and for the insides of the white pixel blocks, black pixel blocks
10 are sampled in the same manner as in step S401 to carry out classification processing similar to that of S402 to S407.

By processing of S401 to S408, black pixel blocks in an image, and white pixel blocks in the
15 black pixel block are sampled, and black pixel blocks are recursively sampled from white pixel blocks inside the "TABLE" and "NONCHAR".

A tree structure is created using pixel blocks existing in each pixel block as child nodes for black
20 pixel blocks and white pixel blocks obtained by carrying out processing shown in Fig. 4. At this time, in the tree structure, attributes classified at steps S402 to S407 are given to black pixel blocks, and an attribute of "WHITE" is given to white pixel
25 blocks. For example, if pixel block sampling is carried out for Fig. 15, then data having a tree structure shown in Fig. 16 is obtained. Furthermore,

in Fig. 16, the number of pixel blocks and the like are partially omitted for simplification of the drawing, but nodes of a large number of pixel blocks actually exist. In the tree of Fig. 16, it is the
5 white pixel block that corresponds to the "WHITE" node, and the attribute of "WHITE" corresponding to the entire image is given to the root of the tree for the sake of convenience. That is, in the tree structure shown in Fig. 16, if the "WHITE" attribute
10 is considered as a background and other attributes such as "CHAR", "TABLE" and "LINE" are considered as foregrounds, the parent node and child node have the background and foreground appearing alternatively in the tree structure of Fig. 16. Furthermore, each
15 node of the tree structure includes area information (segment information) and the attribute of the pixel block.

After the tree structure of pixel blocks is obtained as described above, attention is focused on
20 a black pixel block given the attribute of "NONCHAR" or "TABLE" in the pixel block tree structure, and the sampling of pixel blocks intended for sampling inverted characters on a black ground in this black pixel block is carried out as additional processing
25 in the area division unit 103 at step S304 of Fig. 3. A specific example of processing will be described below using Fig. 6.

At step S601, the possibility that inverted characters exist in a black pixel block A is estimated on the analogy of the geometric characteristics of the focused black pixel block (black pixel block A). Here, if the black pixel density is extremely low, i.e. for a black pixel block like a linear skeletal structure, it is determined that the black pixel block includes no inverted characters. Furthermore, the black pixel density is a value calculated from $\{(\text{the number of pixels having a pixel value of 1 in all segments of the black pixel block}) / P \text{ where } P \text{ is a number of total pixels of all segments of the black pixel block (areas of the black pixel block shown by the example 803 in Fig. 8)}\}$. Complicated analysis processing such as S602 to S608 can be skipped if it can be determined that the possibility that inverted characters exist is very low, by using processing enabling easy calculation such as the black pixel density, thus making it possible to carry out processing quickly.

At step S602, an image R with pixel values (0 and 1) of pixels in the black pixel block A inverted is created. At this time, for pixels constituting the outline of the black pixel block A, the pixel values are kept at 1 without being inverted. Fig. 17 shows an example of creating the image R.

Furthermore, if area division processing (pixel block sampling) in step S303 is carried out using an image scaled down at S302, an image obtained by sampling an area corresponding to the area of the
5 focused black pixel block from the pre-scaledown original, inverting pixel values (0 and 1) for the sampled area (pixels of the outline are not inverted), and subjecting the sampled area for which pixel values have been inverted to OR scaledown processing
10 is defined as an inverted image R in step S602. Otherwise, an inverted character part is likely broken in the image subjected OR scaledown in area division processing. Because a pre-scaledown image is inverted before it is scaled down in this way, the
15 inverted character part can be prevented from being broken and blurred.

At step S603, processing similar to that of S405 is carried out to sample white pixel blocks surrounded by 4 connected lines (white pixel block
20 set C) for the inside of the inverted image R.

At step S604, black pixel blocks (black pixel blocks surrounded by 8 connected lines) are sampled from the inside of the white pixel block set B sampled at step S603. The sampled black pixel block
25 set is defined as C.

At step S605, a white pixel block set inside the pre-inversion black pixel block A is sampled, and

white pixel blocks each having a predetermined size or greater size, of the white pixel block set in the pre-inversion black pixel block A, is considered as not-inverted characters (outlined characters), and
5 are compared with the black pixel block set C obtained at step S604 to remove black pixel blocks overlapping with the white pixel blocks each having a predetermined size or greater size on the coordinate from the set C. Because a white pixel block is
10 sampled from the inside of the pre-insertion black pixel block A to make a determination, it can easily be determined in advance that the block is not an inverted character but a background. In addition, in the black pixel block A in an image obtained by
15 simply subjecting the original image to OR scaledown, even if white pixel blocks are broken, there is no possibility that white pixel blocks separated from each other in the original image are combined into one white pixel block, thus making it possible to
20 correctly take out a part considered as a background (on the other hand, if a black pixel block is sampled in an image obtained by inverting and then scaling down the original image, white pixel blocks separated from each other in the original image may be combined
25 into a black pixel block, and the white pixel background part and inverted character part of the original image may thus be combined if they are close

to each other and in this case, the inverted character may also be removed, and therefore white pixel blocks are sampled from the pre-inversion black pixel block A at S605).

5 An example of processing carried out at steps S602 to S605 is shown in Fig. 9. Provided that a black pixel block sampled by area division processing of S303 from an image obtained by subjecting an original image 901 to OR scaledown at S302 is a block
10 910, an inverted image created by inverting/scaling down the original image of an area corresponding to this black pixel block is an image 920. If an area 912 of a white pixel block existing in the black pixel block 910 (sampled as a black pixel block 922
15 in a white pixel block 921 on the inverted image 920) is clearly considered as a not-inverted character (e.g. it is considered as a not-character if its size is larger than a predetermined size), the black pixel block 922 overlaps in position with the white pixel
20 block 912, and is therefore removed. As a result, a black pixel block set 923 corresponding to the inverted character part remains.

 At step S606, black pixel blocks in the set C are classified as "CHAR" and other attributes based
25 on a determination criterion equivalent to that of S402 (based on whether or not equal to or less than a predetermined threshold value).

At step S607, "CHAR" black pixel blocks are classified as those having very small sizes and others. The number of the former and the latter are N and M, respectively.

5 At this step, N is considered as the number of pixel blocks originating from noises, and N is compared with the number M of other pixel blocks to determine whether the pixel block is a set of characters or not. Here, if M equals 0 or N/M equals
10 a predetermined ratio T or greater ratio, the pixel block is considered as a not-character, and processing proceeds to step S610. In other cases, processing proceeds to step S609.

At step S609, a tree structure having a white
15 pixel block as a parent node is created with "CHAR" black pixel blocks as pixel blocks of inverted characters, and the pixel block tree is updated so that blocks are added just below the original black pixel block A. Furthermore, for the white pixel
20 block as a parent node, the white pixel block B may be simply used, or an area circumscribed with pixel blocks of inverted characters may be defined as the white pixel block.

By using a white pixel block as a parent node
25 in this way, an inverted character can be added as a foreground of the tree structure while retaining the characteristics of the tree structure such that the

background and foreground appear alternatively in the relation between the parent node and the child node.

In the example of Fig. 15, inverted character sampling/determination processing is carried out for
5 three black pixel blocks 1501, 1502 and 1503, and if pixel blocks of inverted characters are sampled from black pixel blocks 1501 and 1503 based on determination form the noise ratio and the like, the tree of Fig. 16 is updated to a tree shown in Fig. 18.
10 A virtual white pixel block inserted at this time is considered as being equivalent to a normal "WHITE" pixel block except that information indicating that it is a ground of an inverted character is included. Such a white pixel block is described as "WHITE (R)"
15 in this embodiment.

Referring to Fig. 3 again, the area definition unit 1033 uses the tree structure of pixel blocks and the classification result to divide images into rectangular areas such as
20 characters/images/tables/lines at step S305. Furthermore, pixel blocks sampled at step S303 and pixel blocks added step S304 retain the characteristics of the tree structure, and therefore can be divided with same processing without
25 discrimination. Processing of classification and area formation of these pixel blocks will be described using Fig. 7.

At step S701, attention is focused on pixel blocks classified as "CHAR", and those existing within a fixed distance longitudinally or laterally are grouped. Rectangles surrounding the groups are character areas. Furthermore, whether a character string in the character area extends in a lateral direction or longitudinal direction is checked. For example, horizontal distances between pixel blocks in the area and left and right closest pixel blocks, and vertical distances between pixel blocks in the area and upper and lower closest pixel blocks are determined, and a direction whose average of the distances is smaller may be defined as the direction of the character string.

At step S702, a set of pixel blocks connected longitudinally or laterally in approximate same sizes, of "NONCHAR" pixel blocks, is detected, and these pixel blocks are grouped as a title character area.

At step S703, pixel blocks whose ratios of black pixels to white pixels in the outline are small, i.e. densities of black pixels are small, of "NONCHAR" pixel blocks, are sampled, and these pixel blocks are defined as a line drawing area.

At step S704, large pixel blocks whose densities of black pixels are high or pixel blocks gathering in an area, of "NONCHAR" pixel blocks, are grouped as a halftone area. The halftone area refers

to a middle tone area such as a photograph. If
"CHAR" or "LINE" pixel blocks are included in the
halftone area, their original areas are abandoned,
and these pixel blocks are integrated into a halftone
5 area.

At step S705, a rectangle surrounding "LINE"
pixel blocks is defined as a line area.

At step S706, a rectangle surrounding "TABLE"
area is defined as a table area.

10 The above processing is performed for all black
pixel blocks. However, the object for grouping is
each set of black pixel blocks existing in one
"WHITE" pixel block.

For example, if a tree structure of pixel
15 blocks shown in Fig. 18 is obtained from the image of
Fig. 21, processing of S701 to S706 is further
carried out to define areas different for each
attribute shown in Fig. 19. At this time, an area
tree structure shown in Fig. 20 is created between
20 areas based on the configuration of the pixel block
tree. In the output result of this area division
processing, coordinate information of each area, and
information of link to an area as a parent, and areas
of children if any are retained.

25 Furthermore, in Fig. 19, the diagonally shaded
text area is a text area sampled as inverted
characters. This can be identified from the fact

that it is a text existing below WHITE (R) in the tree structure of Fig. 20 from the output result. However, processing of S701 to S706 is carried out without discrimination of inverted areas, and
5 therefore decision algorithms and the like can be made common for both non-inverted areas and inverted areas.

As described above, inverted characters (outlined characters) can be managed with a
10 hierarchical tree structure same as that of normal characters.

In addition, when area division processing for dividing an image obtained by scanning a paper into part elements having different natures such as
15 characters, graphics, photographs and tables is carried out, white-on-black character areas can be sampled using an area sampling method similar to that for black-on-white character areas.